

Electromagnetism Reference: Curvilinear Co-ordinates

Mike Hughes

These are some useful definitions for curvilinear co-ordinate systems.

Coordinate Systems Elements

Cylindrical Coordinates (r, θ, z)

$$x = r \cos \theta, \quad y = r \sin \theta, \quad z = z$$

Volume Element

$$dV = r \, dr \, d\theta \, dz$$

Surface Element

$$dS = r \, d\theta \, dz \, \hat{r}$$

Spherical Coordinates (r, θ, ϕ)

$$x = r \sin \theta \cos \phi, \quad y = r \sin \theta \sin \phi, \quad z = r \cos \theta$$

Volume Element

$$dV = r^2 \sin \theta \, dr \, d\theta \, d\phi$$

Surface Element

$$dS = r^2 \sin \theta \, d\theta \, d\phi \, \hat{r}$$

Differential Operators

Gradient

Cylindrical Coordinates

$$\nabla f = \frac{\partial f}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{\theta} + \frac{\partial f}{\partial z} \hat{z}$$

Spherical Coordinates

$$\nabla f = \frac{\partial f}{\partial r} \hat{r} + \frac{1}{r} \frac{\partial f}{\partial \theta} \hat{\theta} + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \phi} \hat{\phi}$$

Divergence

Cylindrical Coordinates

$$\nabla \cdot \vec{A} = \frac{1}{r} \frac{\partial}{\partial r} (r A_r) + \frac{1}{r} \frac{\partial A_\theta}{\partial \theta} + \frac{\partial A_z}{\partial z}$$

Spherical Coordinates

$$\nabla \cdot \vec{A} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 A_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta A_\theta) + \frac{1}{r \sin \theta} \frac{\partial A_\phi}{\partial \phi}$$

Curl

Cylindrical Coordinates

$$\nabla \times \vec{A} = \begin{vmatrix} \hat{r} & \hat{\theta} & \hat{z} \\ \frac{\partial}{\partial r} & \frac{1}{r} \frac{\partial}{\partial \theta} & \frac{\partial}{\partial z} \\ A_r & r A_\theta & A_z \end{vmatrix}$$

Spherical Coordinates

$$\nabla \times \vec{A} = \frac{1}{r \sin \theta} \begin{vmatrix} \hat{r} & r \hat{\theta} & r \sin \theta \hat{\phi} \\ \frac{\partial}{\partial r} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ A_r & r A_\theta & r \sin \theta A_\phi \end{vmatrix}$$